

Molecular Replacement

Andrey Lebedev
CCP4

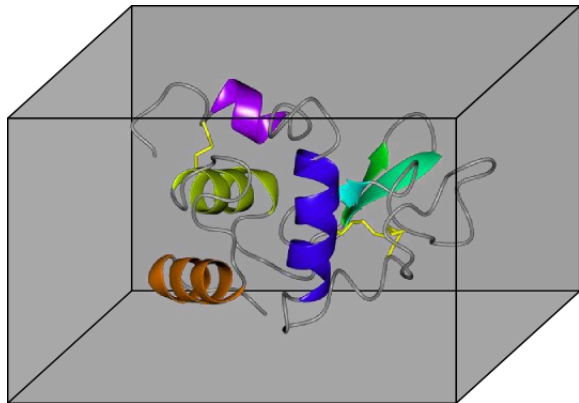
<http://www.ccp4.ac.uk/tutorials/>

Basic phasing tutorials

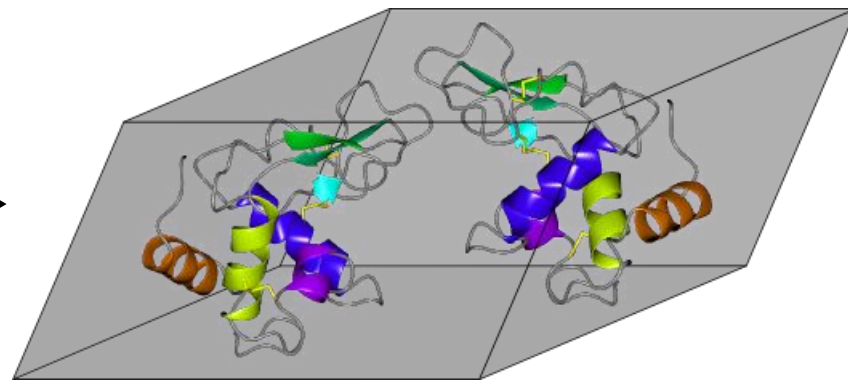
(Includes both MR and Experimental Phasing)

MR Problem

Known crystal structure



New crystal structure



Given:

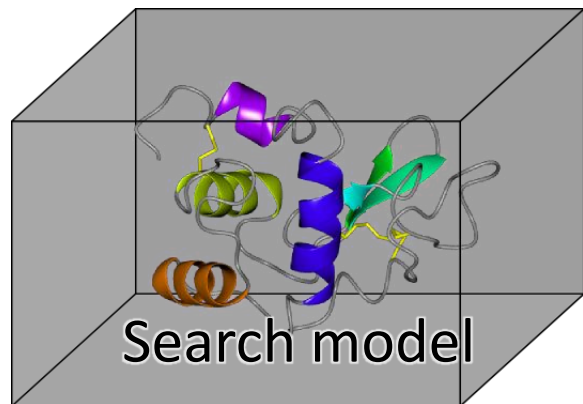
- Crystal structure of a homologue
- New X-ray data

Find:

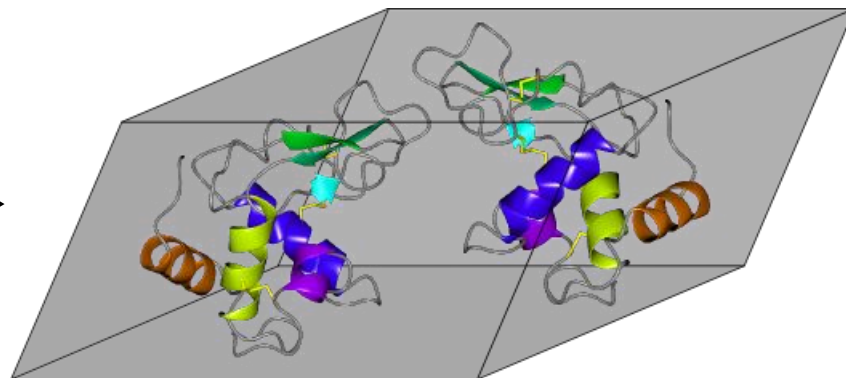
- The new crystal structure

MR Technique

Known crystal structure



New crystal structure



Method:

- 6-dimensional global optimisation
 - one 6-d search for each molecule in the AU
 - >> split further to orientation + translation searches = 3 + 3?

Required:

- Scoring
 - the match between the data and an (incomplete) crystal model
 - ideally: the highest score = the correct model

Real and Reciprocal spaces

Two reasons to discuss the real and reciprocal spaces

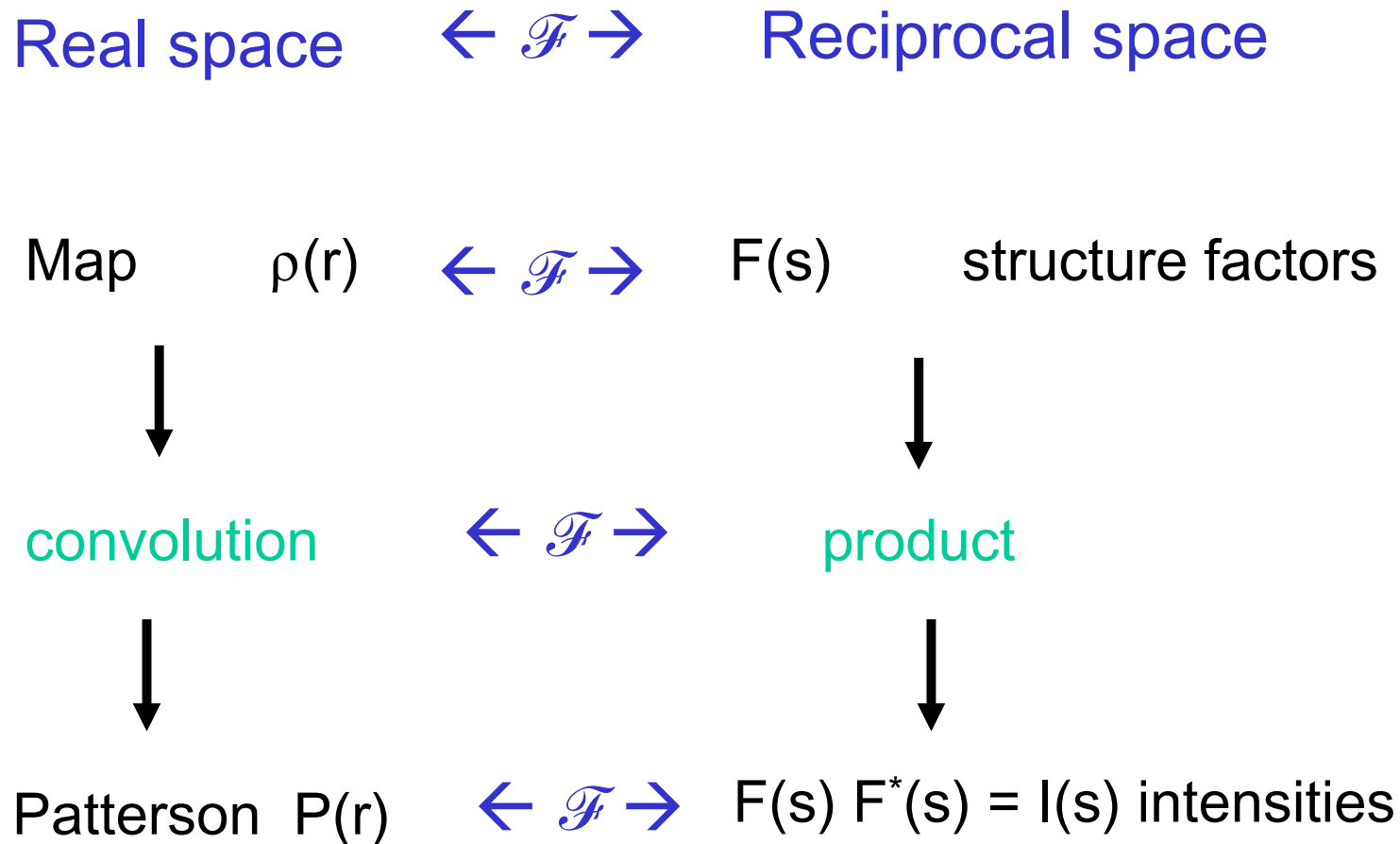
Perception of crystallographic methods

- Many concepts formulated in one space have their counterparts in another space
- The concepts formulated in real space are sometimes more intuitive

Terminology vs. methods

- Sometimes names are taken from real space but assume calculations in the reciprocal space:
 - "Search in the electron density"
 - "Patterson search"

Functions in Real and Reciprocal spaces



Next few slides: F and I as experimental data

Structure factors and Electron density map

Structure factors $F(h,k,l)$

- A discrete complex function in the reciprocal space

Each F :

- Complex number:

$$F = A + iB$$

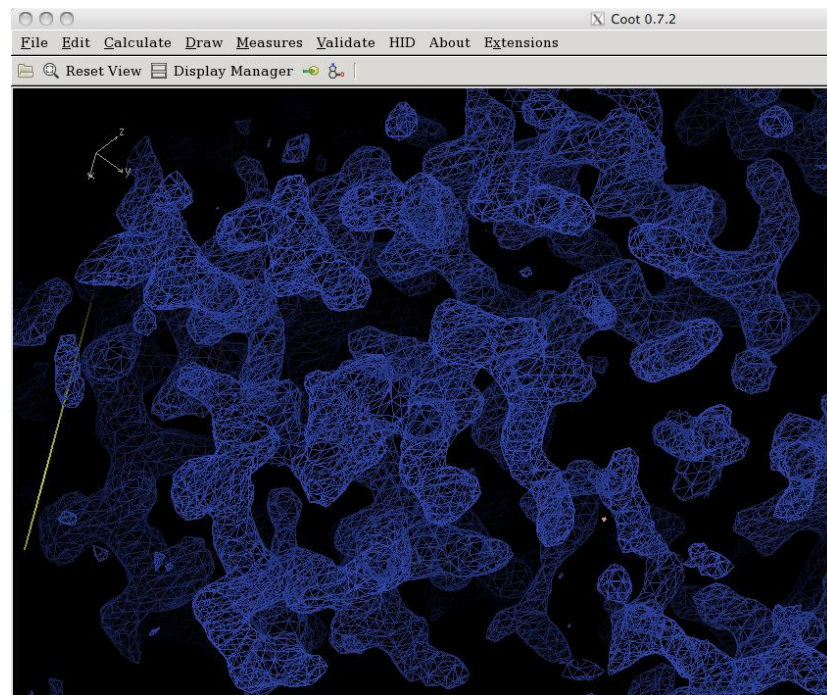
- Can be expressed via structure amplitude and phase

$$F = |F| \exp(if)$$

	h	k	l	FreeR_flag	F	SIGF	parrot.F_phi.F	parrot.F_phi.phi
11684	14	2	37	18	146.69	3.12	122.01	22.80
11685	14	2	38	7	134.61	3.26	94.11	164.66
11686	14	2	39	7	41.34	10.84	104.88	346.16
11687	14	2	40	12	195.94	3.04	192.02	149.45
11688	14	2	41	3	117.36	3.76	87.03	39.69
11689	14	2	42	14	108.63	3.37	41.80	142.52
11690	14	2	43	13	194.47	2.93	252.73	17.39
11691	14	2	44	12	90.95	4.05	57.40	212.22

Electron density map

- periodic 3-d function in real space



is directly interpretable

- model building
- real-space fitting of fragments

Intensities and Patterson map

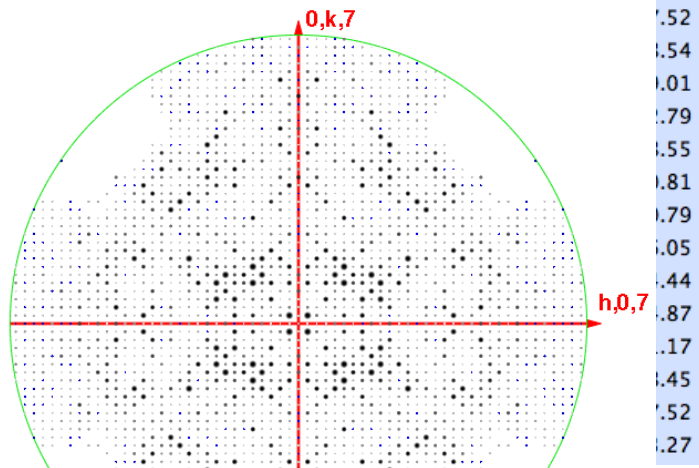
Intensities $I(h,k,l)$

- 3-d discrete real function in the reciprocal space

Open Print PDF/PS Copy General Summary HKL

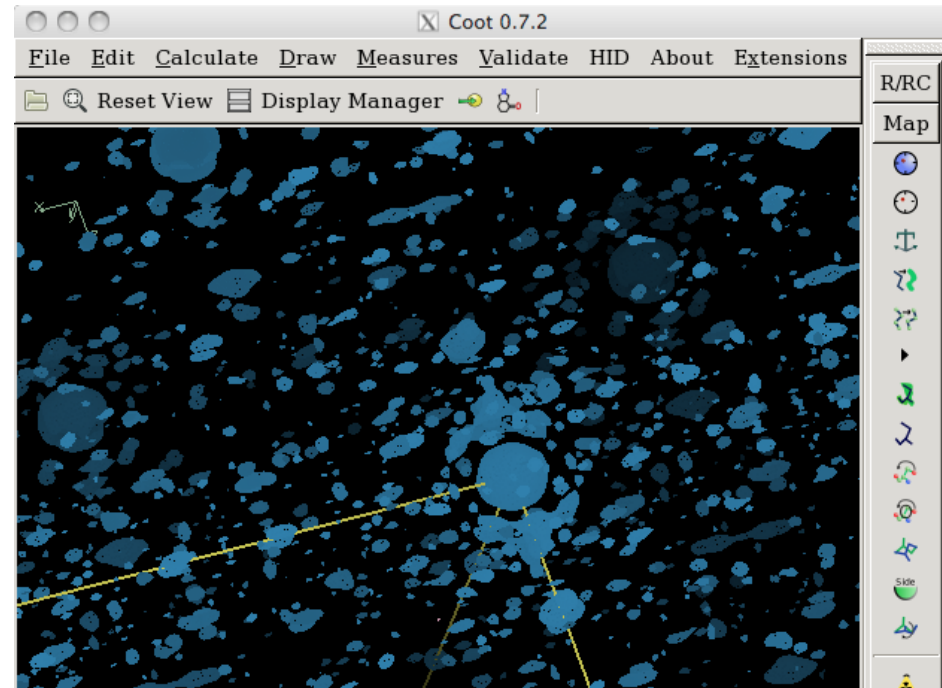
Title: P222

	h	k	l	F _o	F _c	SIG	IMEAN	SIG/MEAN
13671	12	9	34	15	145.37	38.51	54.57	45.85
13672	12	9	35	11	144.03	38.25	54.00	45.05
13673	12	10	0	15	131.82	49.54	68.47	44.37
13674	12	10	1	13	88.30	28.53	-38.02	29.04
13675	12	10	2	13	239.79	29.38	156.79	33.71
13676	12	10	3	3	356.73	21.77	328.07	38.83
13677	12	10	4	3	112.79	33.04	8.13	18.69



Patterson map:

- 3-d function in real^(*) space



- Nothing reminds a protein molecule
- **Model building**, residue by residue, is **impossible**

MR: Two distinct cases dependent on availability of phases

- Data = structure factors (**include phases**)
 - "**Search in the electron density**"
 - Electron density maps are compared: calculated vs. observed
 - Can be treated in a more straightforward way (model building)
 - » Useful in special cases
- Data = observed intensities (**no phases**)
 - "**Patterson search**"
 - Patterson maps are compared: calculated vs. observed
 - Direct model building is impossible in the absence of phases
 - » The most common case of MR

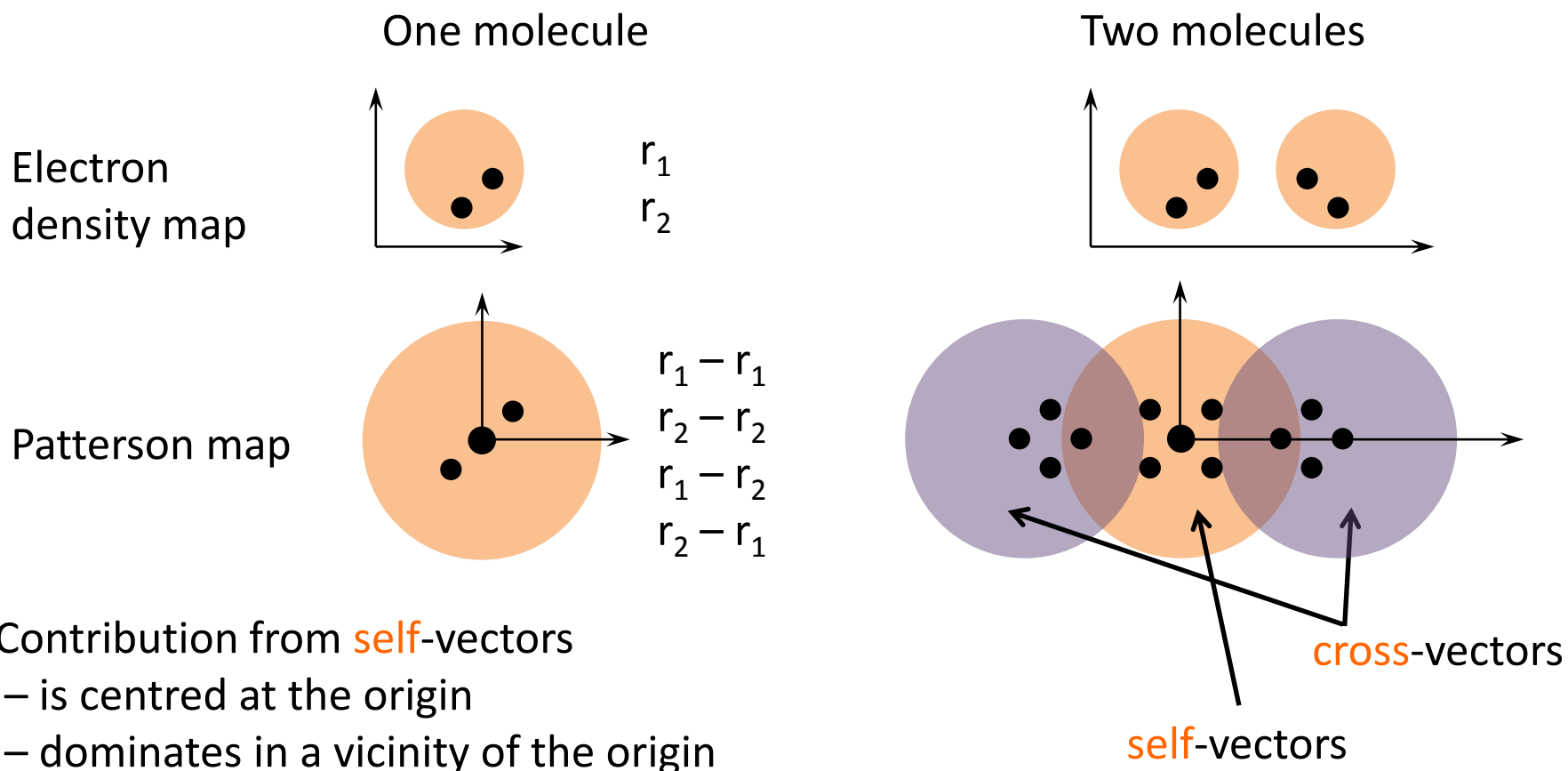
As a rule, all computations are in the reciprocal space

Self and cross vectors

Electron density map = peaks from all atoms

Patterson map = peaks from all interatomic vectors

- **self**-vectors: vectors between atoms belonging to the same molecule
- **cross**-vectors: vectors between atoms belonging to different molecules



What can be seen to be separated?

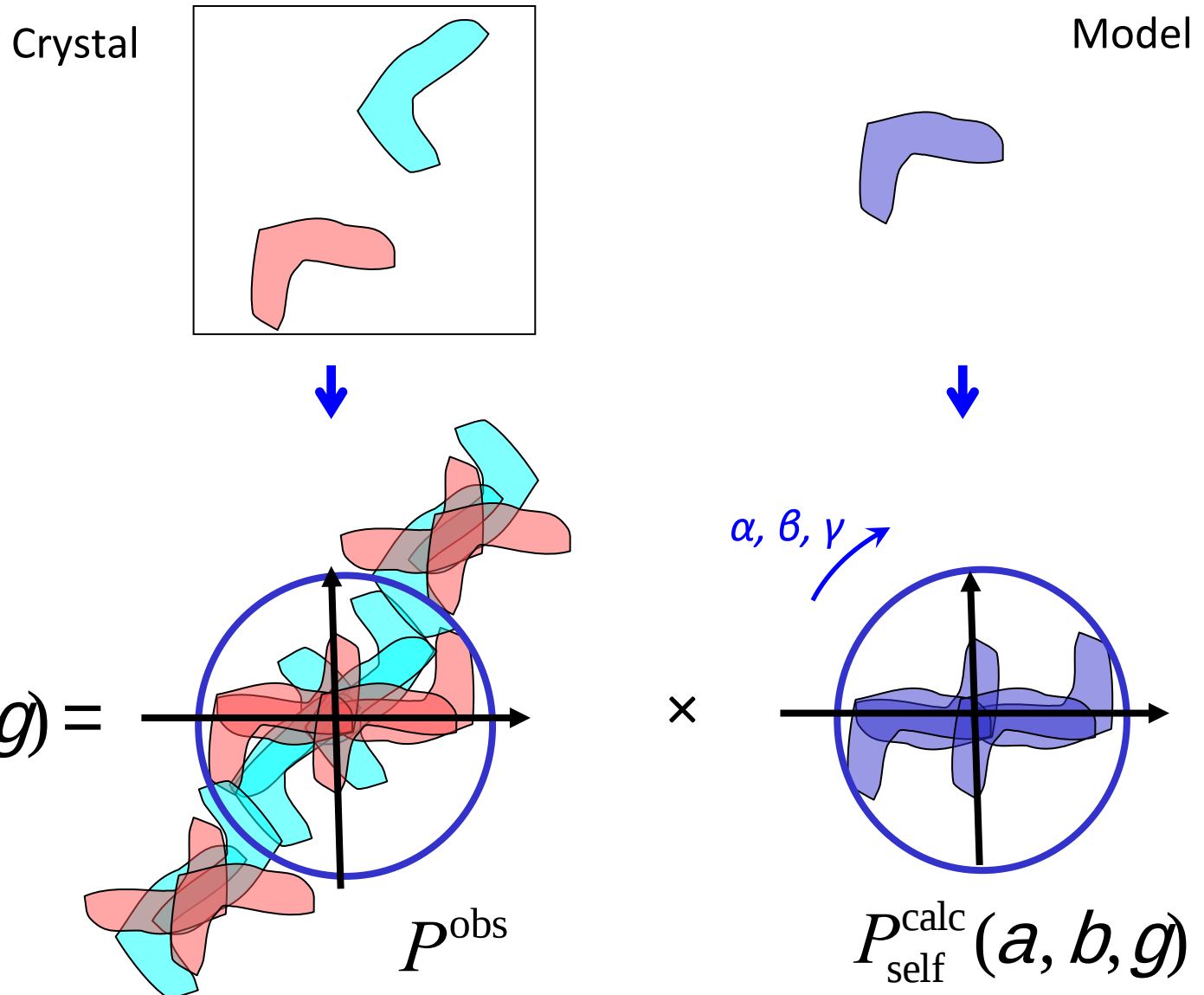
Electron density maps:

- Peaks from atoms or larger fragments are separated in space
 - Model building is possible

Patterson map:

- Contribution from **self**-vectors is centred at the origin
- **Self**-vectors are, in average, shorter than **cross**-vectors
 - Peaks from **self**-vectors dominates in a vicinity of **the origin**
 - Peaks from **cross**-vector dominates **away from the origin**
- One 6-dimensional search splits into
 - Rotation Function: 3-dimensional search (using **self**-vectors)
 - Translation Function: 3-dimensional search (using **cross**-vectors)

Rotation Function



Rotation Function

$$RF(a, b, g) = \iiint P^{\text{obs}} - P^{\text{calc}}_{\text{self}}(a, b, g) dr^3$$

$P^{\text{calc}}_{\text{self}}(a, b, g)$ contains only

- self-vectors

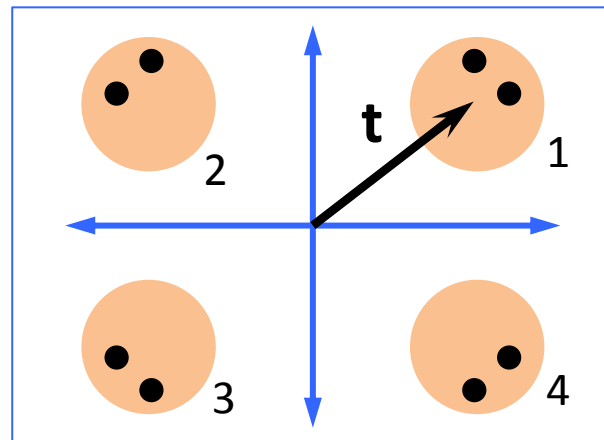
P^{obs} contains

- self-vectors (mostly signal)
- cross-vectors (noise)

Translation Function

Analytical steps

- The centre of molecule 1
 - Parameter t
- Centres of molecules 2, 3 and 4
 - form symmetry operations



- $F_h^{\text{calc}}(\mathbf{t}), I_h^{\text{calc}}(\mathbf{t})$
- $TF(\mathbf{t}) = \hat{\mathbf{a}}_h I_h^{\text{obs}} \cdot I_h^{\text{calc}}(\mathbf{t})$
- Can be converted to a form:

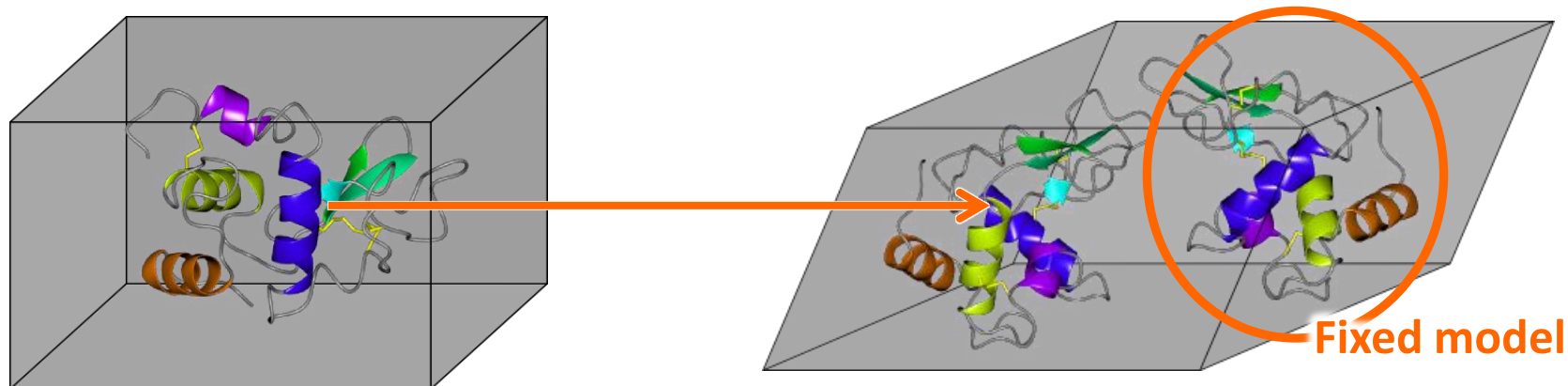
$$TF(\mathbf{t}) = \hat{\mathbf{a}}_h G_h \exp(2\pi i \mathbf{h} \cdot \mathbf{t})$$

- FFT techniques can be applied

Numerical calculations

- G_h
- **FFT**: $G_h \rightarrow TF(\mathbf{t})$
- Peak search in $TF(\mathbf{t})$: best $\mathbf{t}$

Fixed partial model



Almost the same equation as for a single molecule search,

$$TF(\mathbf{t}) = \hat{\mathbf{a}}_{\mathbf{h}} I_{\mathbf{h}}^{\text{obs}} \cdot \left| F_{\mathbf{h}}^{\text{fixed}} + F_{\mathbf{h}}^{\text{calc}}(\mathbf{t}) \right|^2$$

Again, can be converted to a form:

$$TF(\mathbf{t}) = \hat{\mathbf{a}}_{\mathbf{h}} G_{\mathbf{h}} \exp(2\pi i \mathbf{h} \cdot \mathbf{t})$$

and **FFT** technique can be used

Translation Function

$$TF(\mathbf{t}) = \iiint P^{\text{obs}} \cdot P_{\text{cross}}^{\text{calc}}(\mathbf{t}) d\mathbf{r}^3$$

$P_{\text{cross}}^{\text{calc}}(\mathbf{t})$ contains only

- **cross**-vectors

P^{obs} contains

- **self**-vectors (**noise**)
- **cross**-vectors (mostly **signal**)

Packing considerations

Molecules in the crystal **do not overlap**

How can we use this information?

» Patterson map does not explicitly reveal molecular packing

Reject MR solutions

- Restrict distance between centres of molecules
- Count close interatomic contacts

Modify TF

- Divide by Overlap Function
- Multiply by Packing function

Fast Packing Function

Estimation of overlap

- Using mask from search model
- FFT

Packing Function

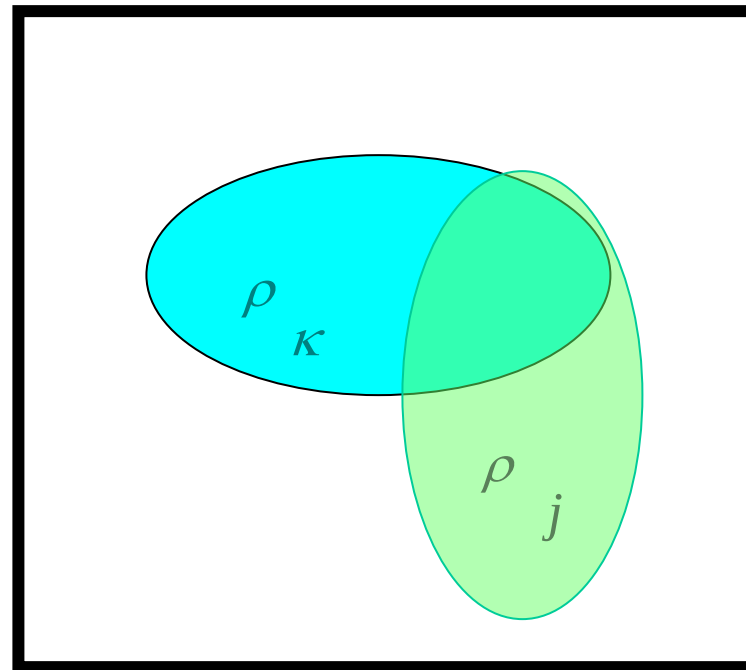
$$PF = 1 - \text{overlap}$$

Modified Translation Function

$$TF' = TF \times PF$$

Peak search

- Using TF'
- No irrelevant peaks are passed to rescoring step

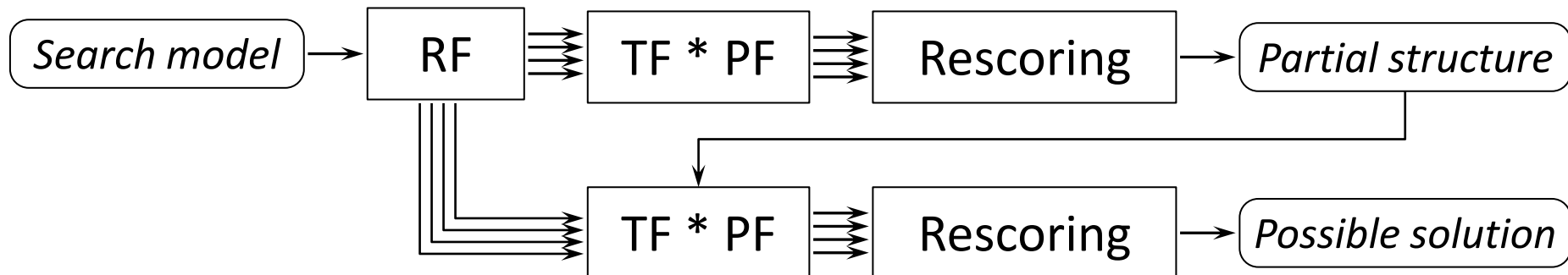


Implemented in *MOLREP*

A conservative MR protocols for two copies of a model

As implemented in *MOLREP*

Intensities $\longrightarrow$ all steps



$$RF = \sum_{hkl} w * I_o * I_c(\alpha\beta\gamma)$$

$$TF = \sum_{hkl} w * I_o * I_c(xyz)$$

Rescoring: Correlation Coefficient* PF

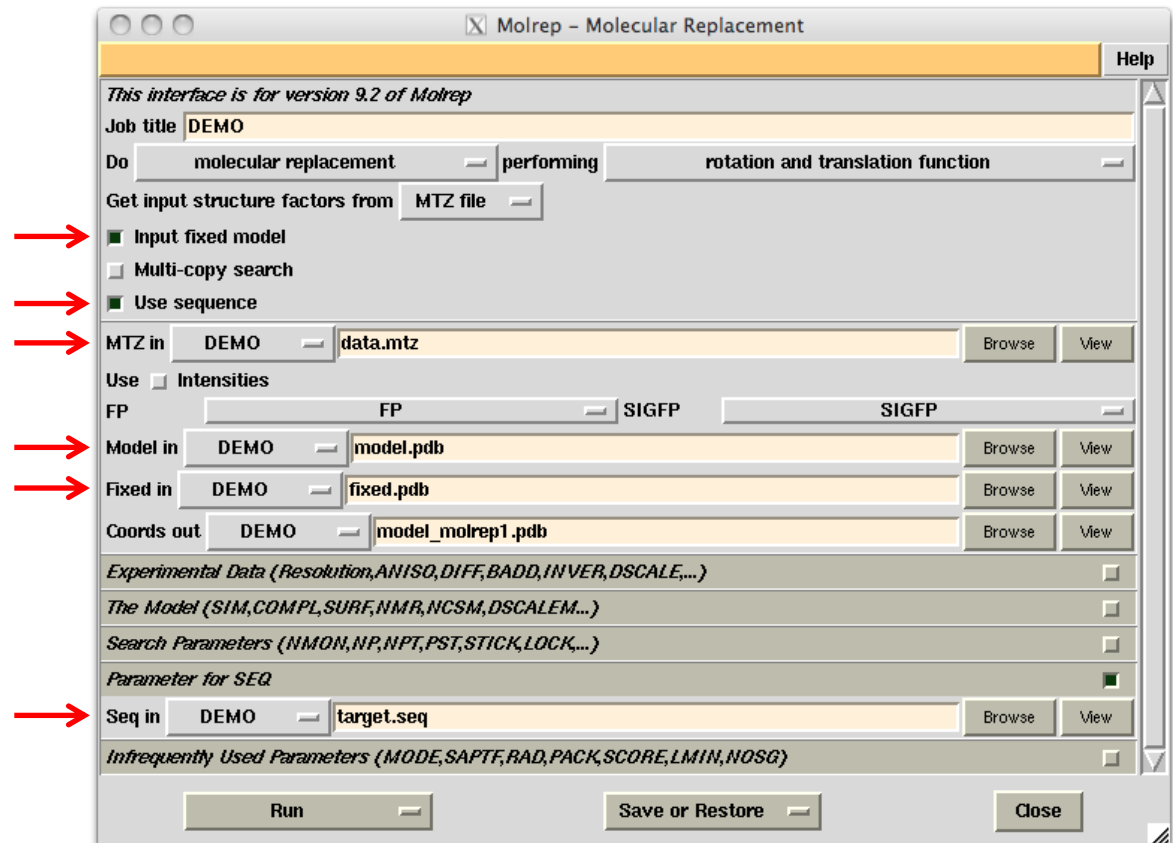
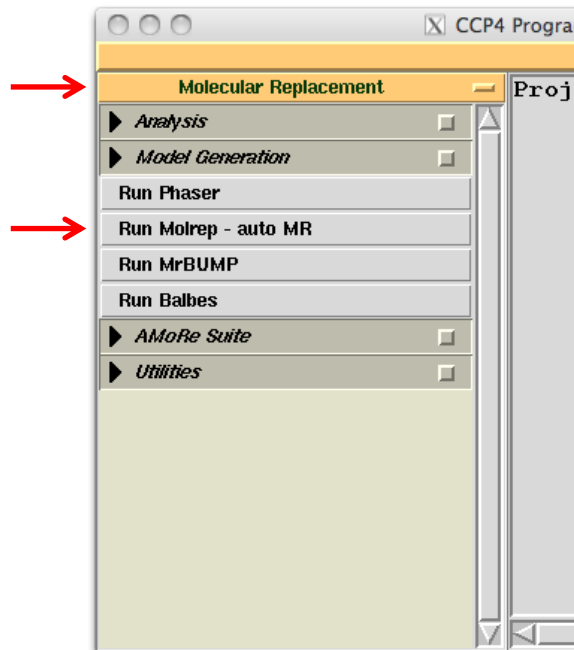
Molrep

Alexey Vagin

YSBL University of York

Molrep

```
molrep -f data.mtz -m model.pdb -mx fixed.pdb -s target.seq
```



Molrep default protocol

```
molrep -f data.mtz -m model.pdb -mx fixed.pdb -s target.seq
```

- model correction if sequence provided
- defines the number of molecules per AU
- modification of the model surface
- anisotropic correction of the data
- weighting the data according to model completeness and similarity
- check for pseudotranslation and use it if present
- 30+ peaks in Cross RF for use in TF (accounts for close peaks)
- applied packing function
- make use of partial structure (fixed model)



Molecular Replacement

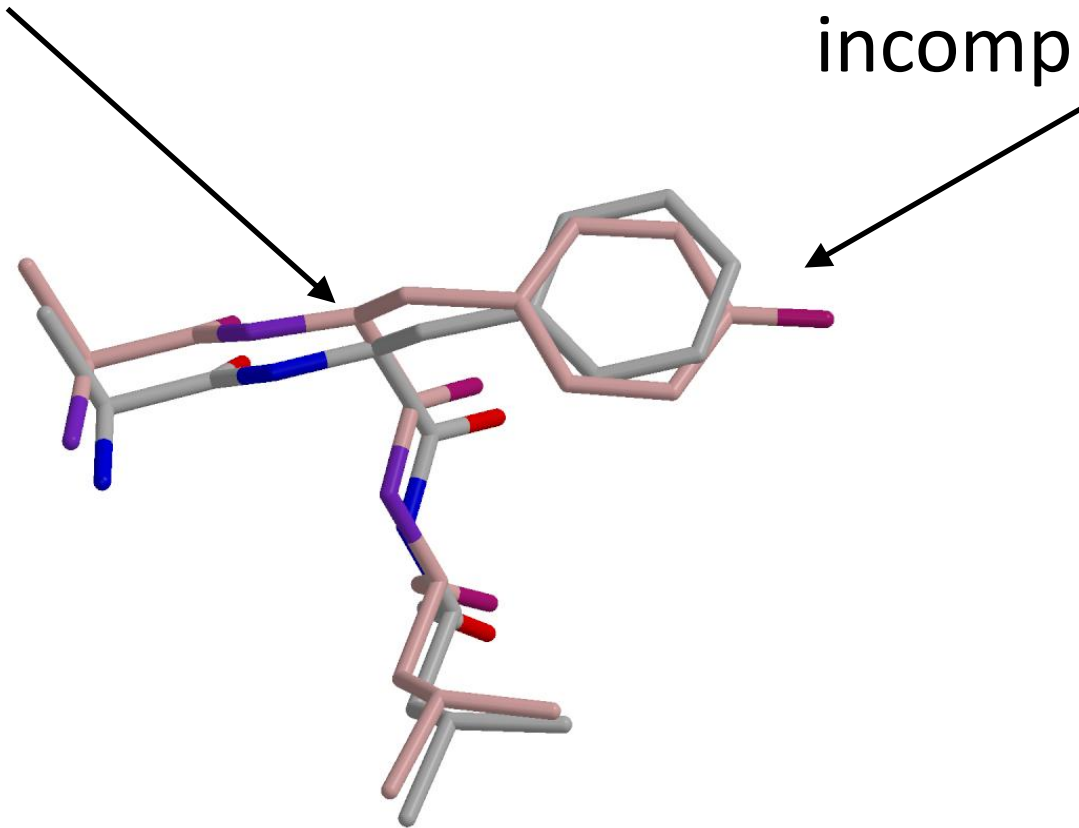
Gábor Bunkóczi



Model error

Position errors

Model incompleteness

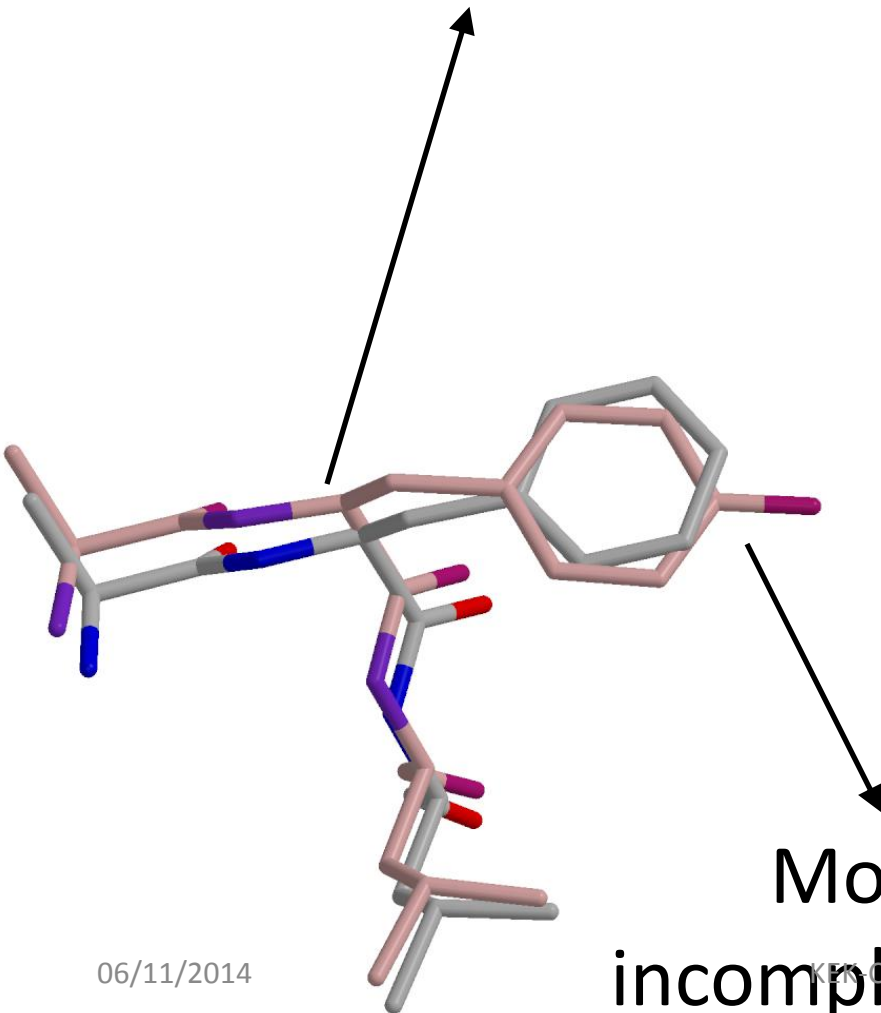
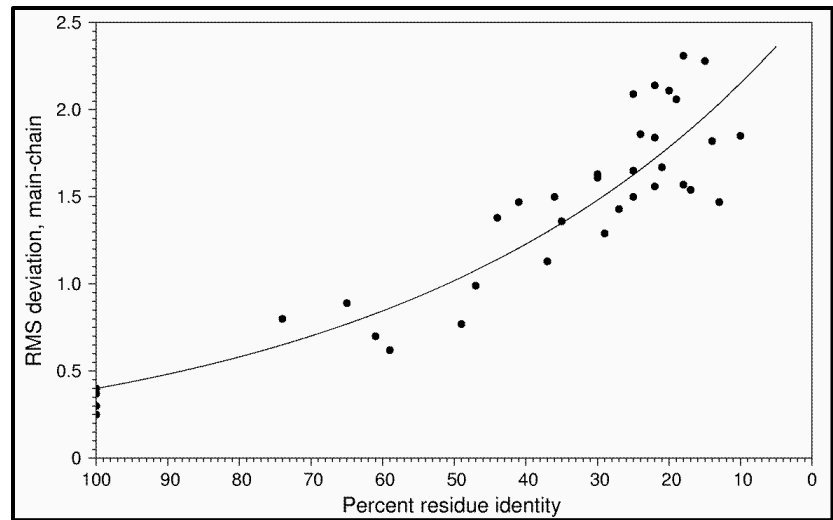




Model error

Position errors

Calculate from
sequence identity
(Chothia & Lesk)



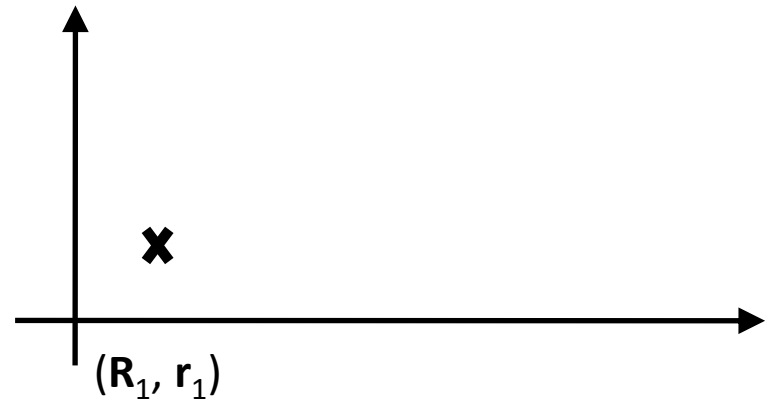
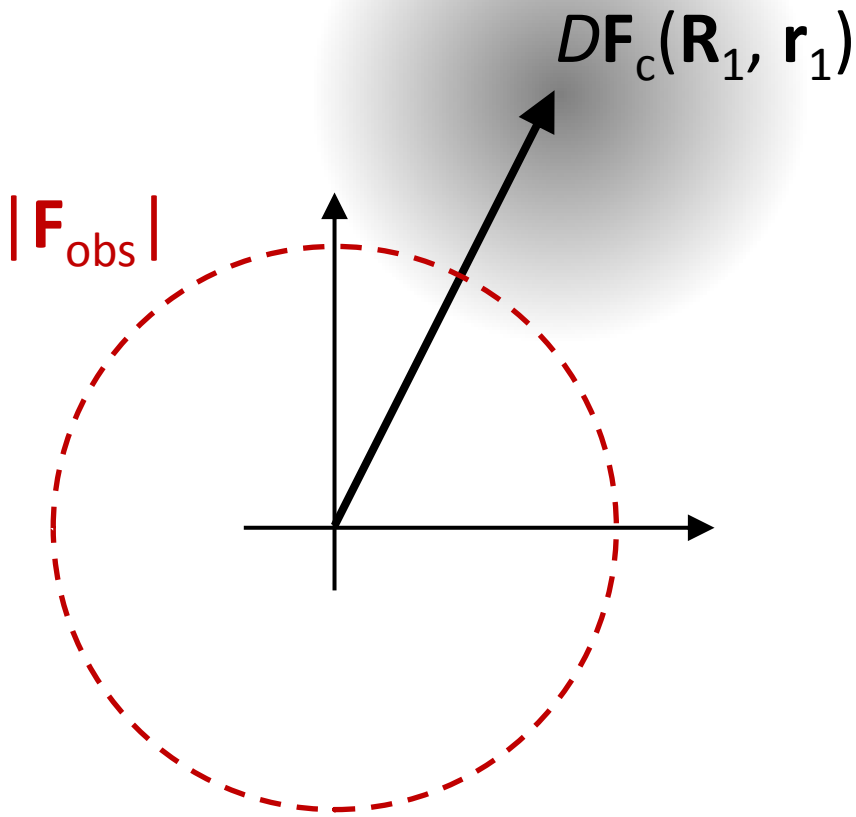
Model
incompleteness

Calculate from unit
cell composition



Likelihood of $|\mathbf{F}_{\text{obs}}|$

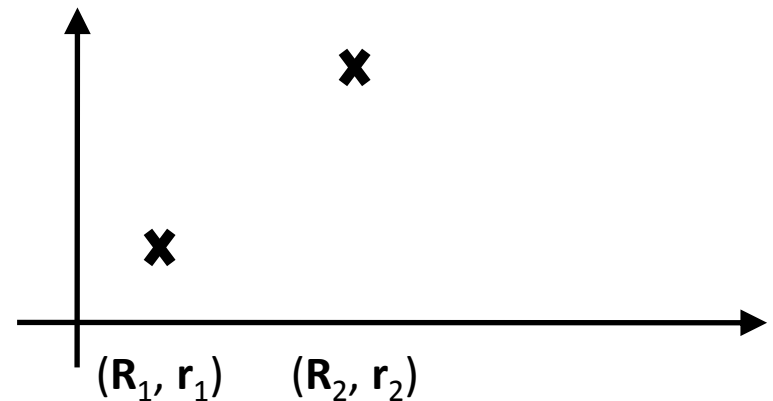
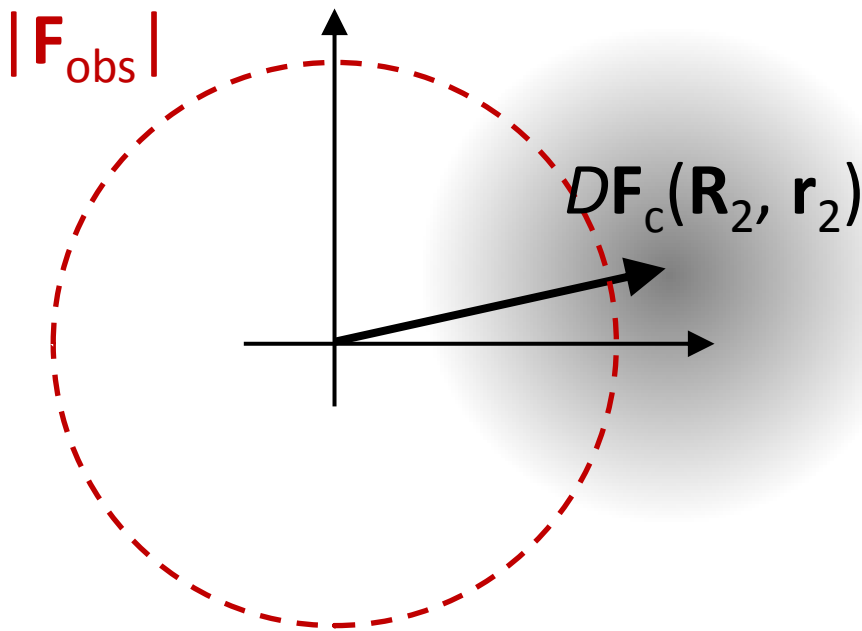
(given $\mathbf{R}_1, \mathbf{r}_1, D, \sigma_\Delta$)





Likelihood of $|\mathbf{F}_{\text{obs}}|$

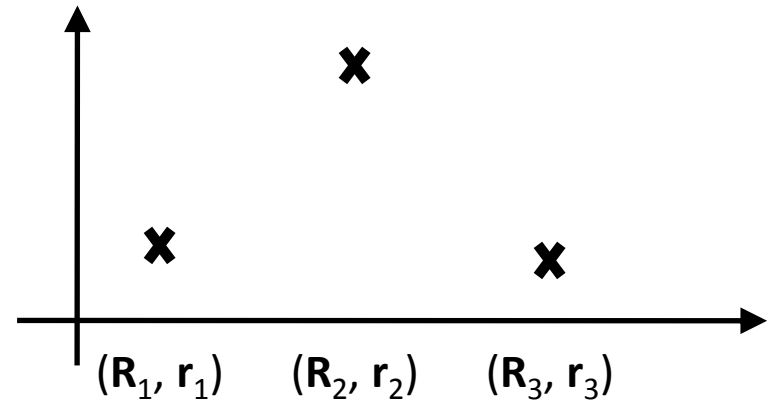
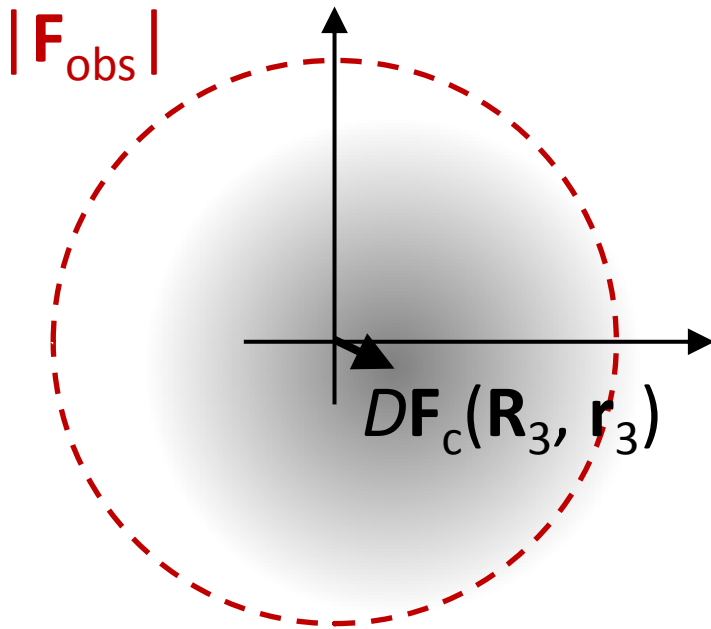
(given $\mathbf{R}_2, \mathbf{r}_2, D, \sigma_\Delta$)





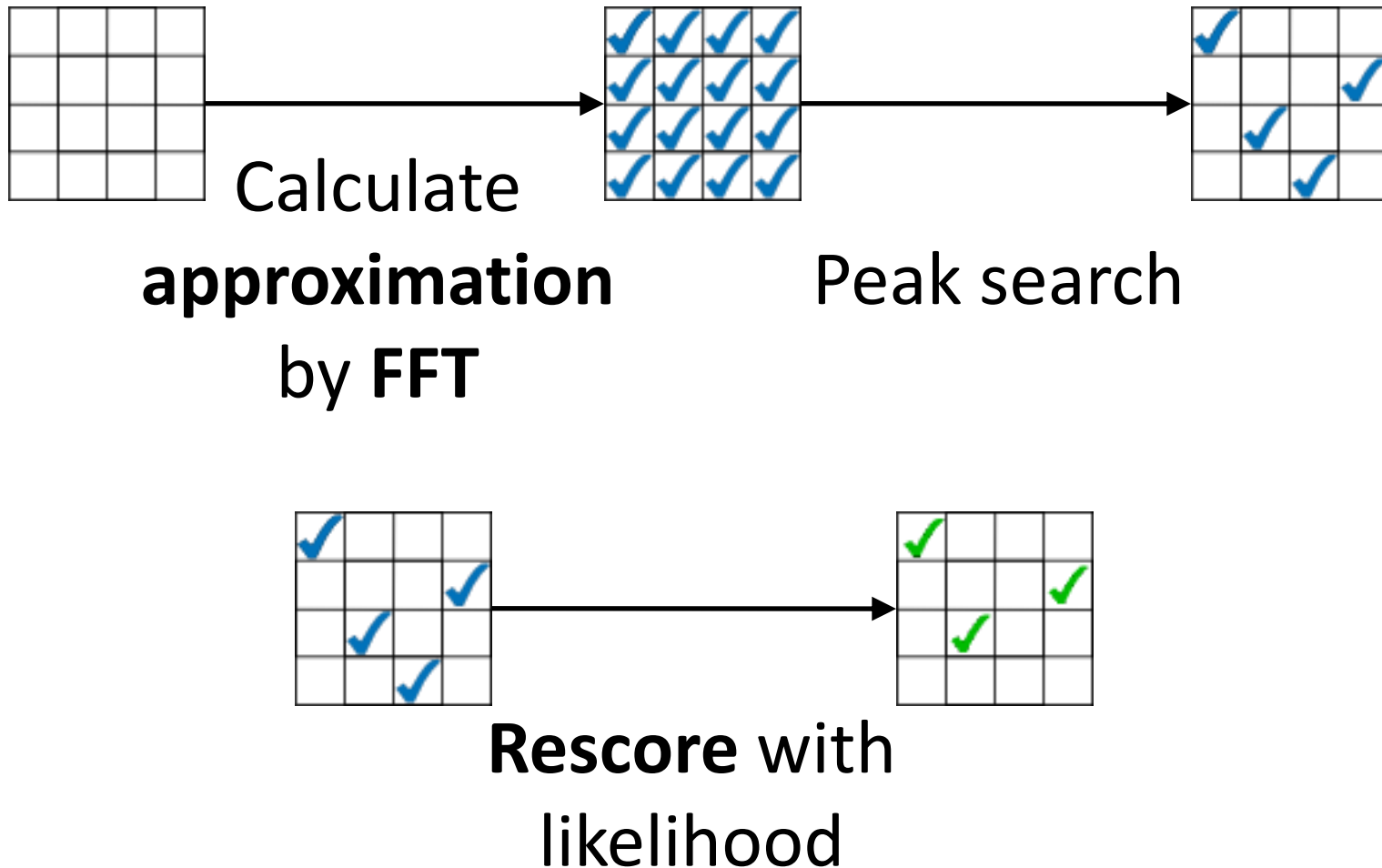
Likelihood of $|\mathbf{F}_{\text{obs}}|$

(given $\mathbf{R}_3, \mathbf{r}_3, D, \sigma_\Delta$)





Likelihood usage

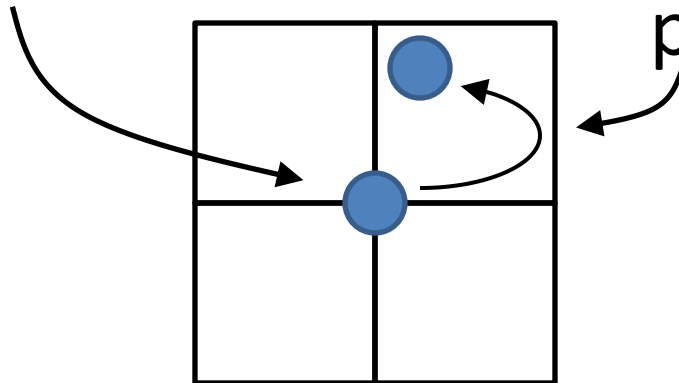




Refinement – Likelihood target

The rotation and translation functions were performed on a (not very fine) grid

The solution can be improved if the grid is taken away and the rotational and translational parameters optimized





Fast search

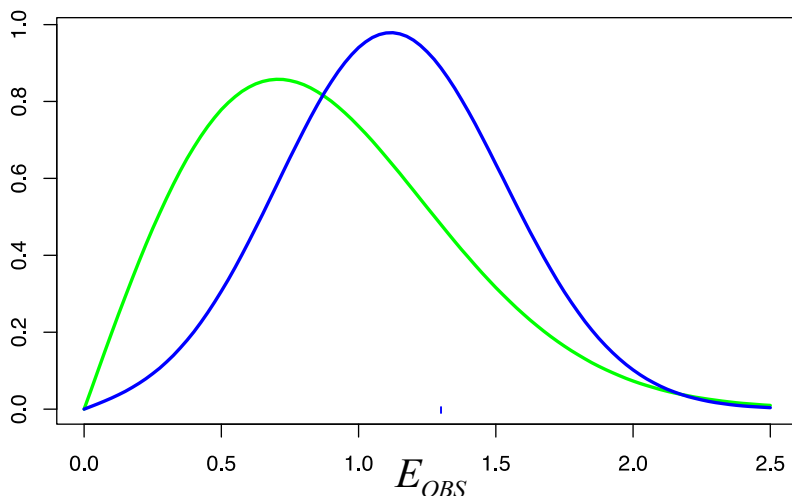
Back to classical MR? Not quite

Advantages of using Likelihood approach

- Final scoring is the most robust
- Maximum consistency between preliminary and final scoring

A way to push boundaries of the method

Log Likelihood Gain (LLG)

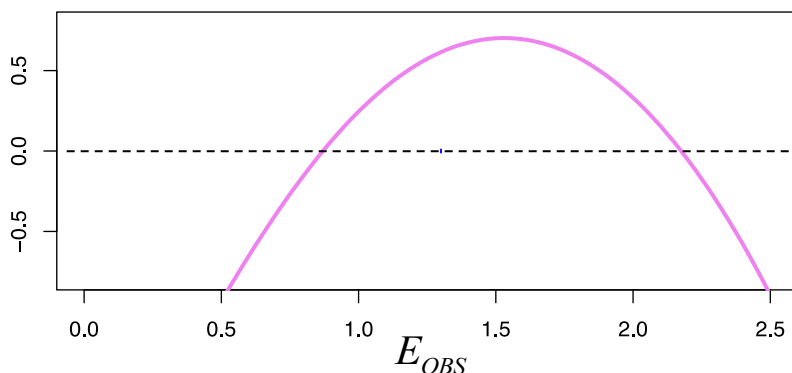


- $p_1 = p(E_{OBS} | E_{CALC} = 1.3, s_A = 0.8)$

The model is assumed to be good

- $p_0 = p(E_{OBS} | E_{CALC} = \text{Any}, s_A = 0)$

The model is assumed to be random



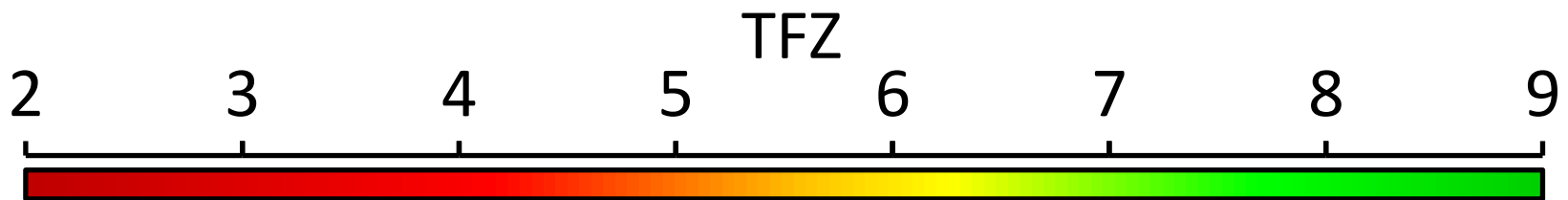
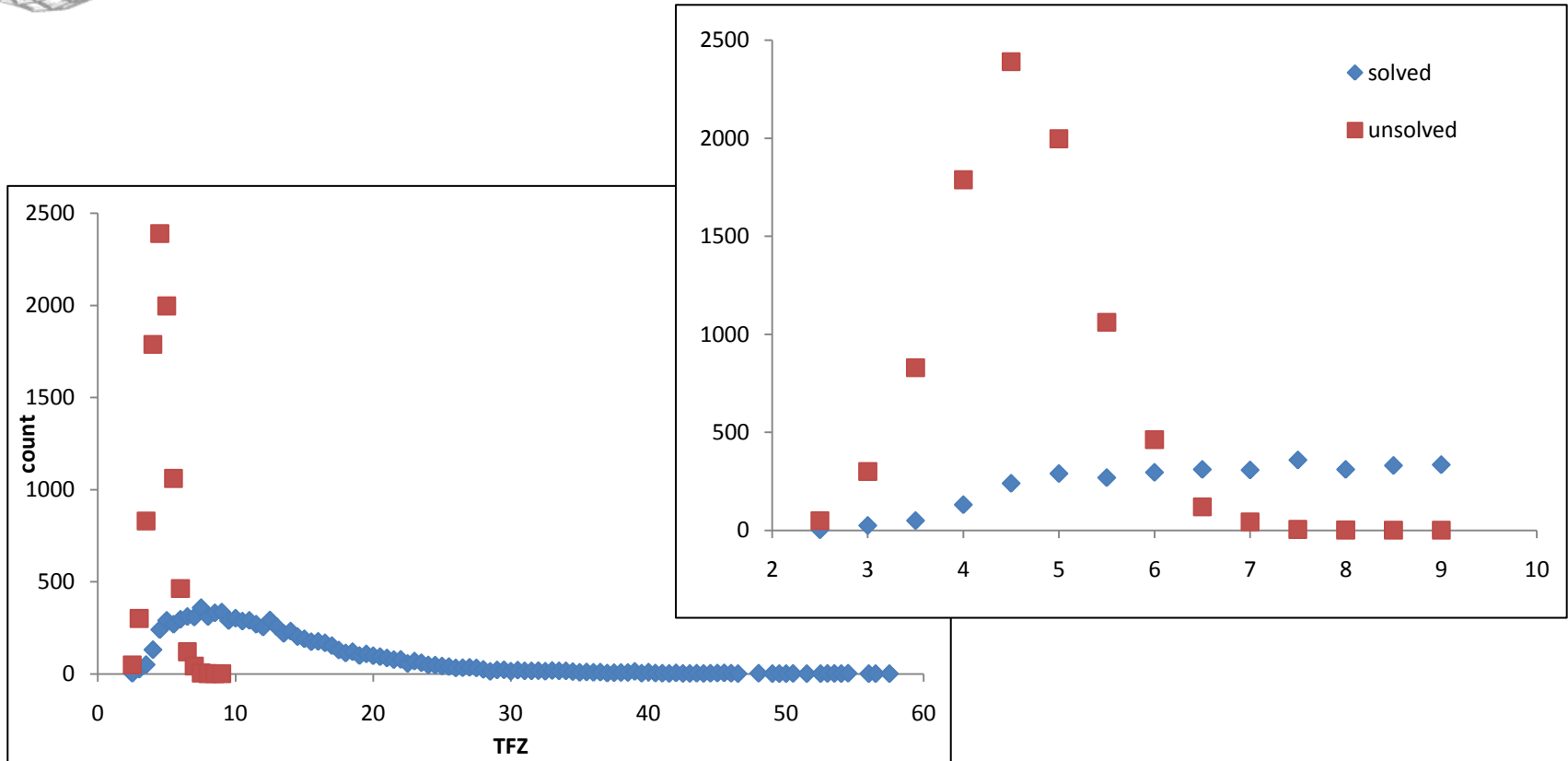
- $LLG_1 = \log p_1 - \log p_0$

Log Likelihood Gain (LLG)

- An empirical criterion $LLG > 70$:
 - identification of the MR successful run
 - prediction of sufficient amount of data (resolution cut-off)

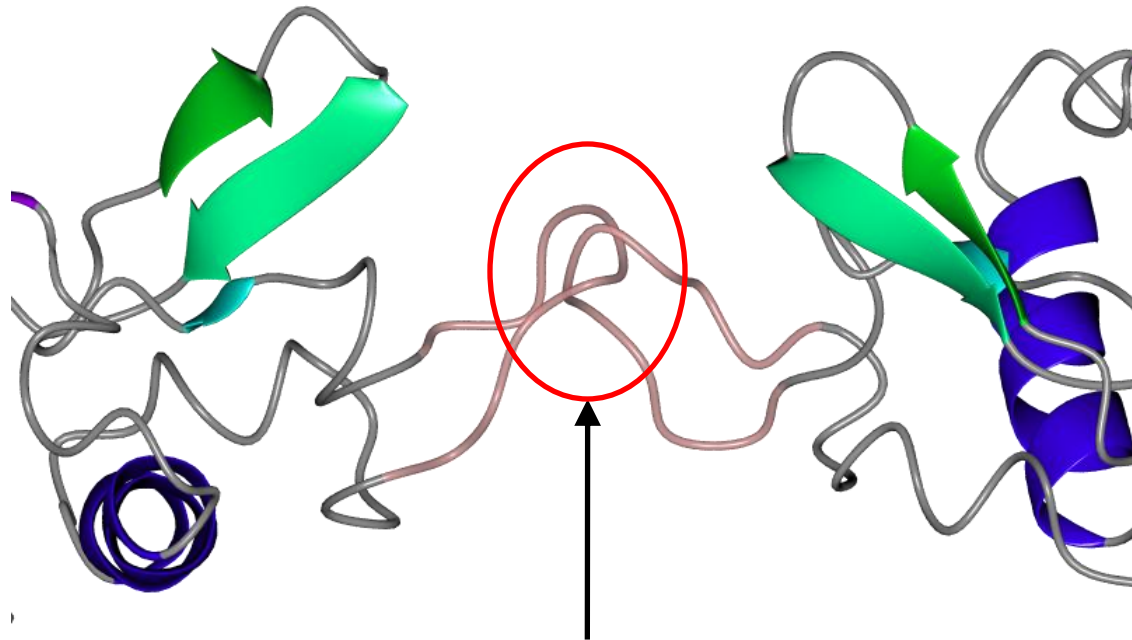


Identifying solutions





Packing



A small number of clashes
is acceptable



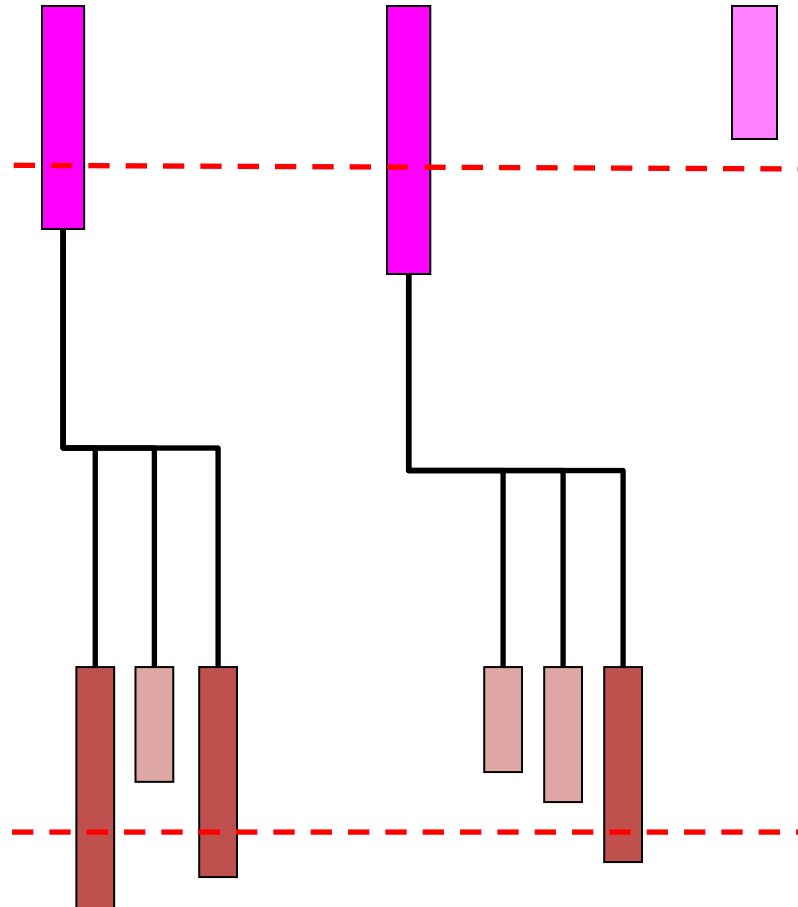
Tree search with pruning

1st component

Pruned
Propagated

Perform search

2nd component



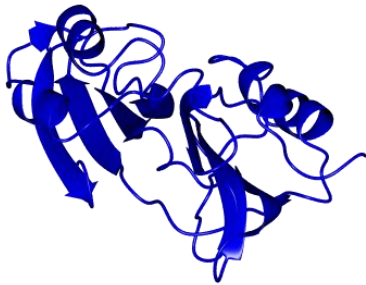


Model search order



65% of structure
35% identical model

**Better model if data
resolution is low**



35% of structure
50% identical model

**Better model if data
resolution is high**

Determined automatically!

If automated MR does not work

MR combination with other techniques

- Automated MR is quite advanced, is convenient, but
 - still may fail to produce complete model
 - may be very slow if there are many components to position
 - limited feedback from user

In general, automated MR is good for finding partial model, but it is not the most efficient way to generate a nearly complete model.

- Combine MR with
 - refinement of partial model
 - density improvement
 - manual or automated model building

MR pipelines: combinations with other automated methods

- Specialised MR techniques can be useful

Specialised MR techniques

- Handling Translational Non-Crystallographic symmetry
 - Non-origin peaks in the Patterson map indicate the presence of TNCS
 - Molecules related by TNCS can be found in one go as they have the same orientation
- Locked RF and TF
 - Using point symmetry of oligomers
- Exhaustive and stochastic searches
- Using phase information in MR
- Self Rotation Function

Refinement refinement + Phased MR

Partial structure

Search model



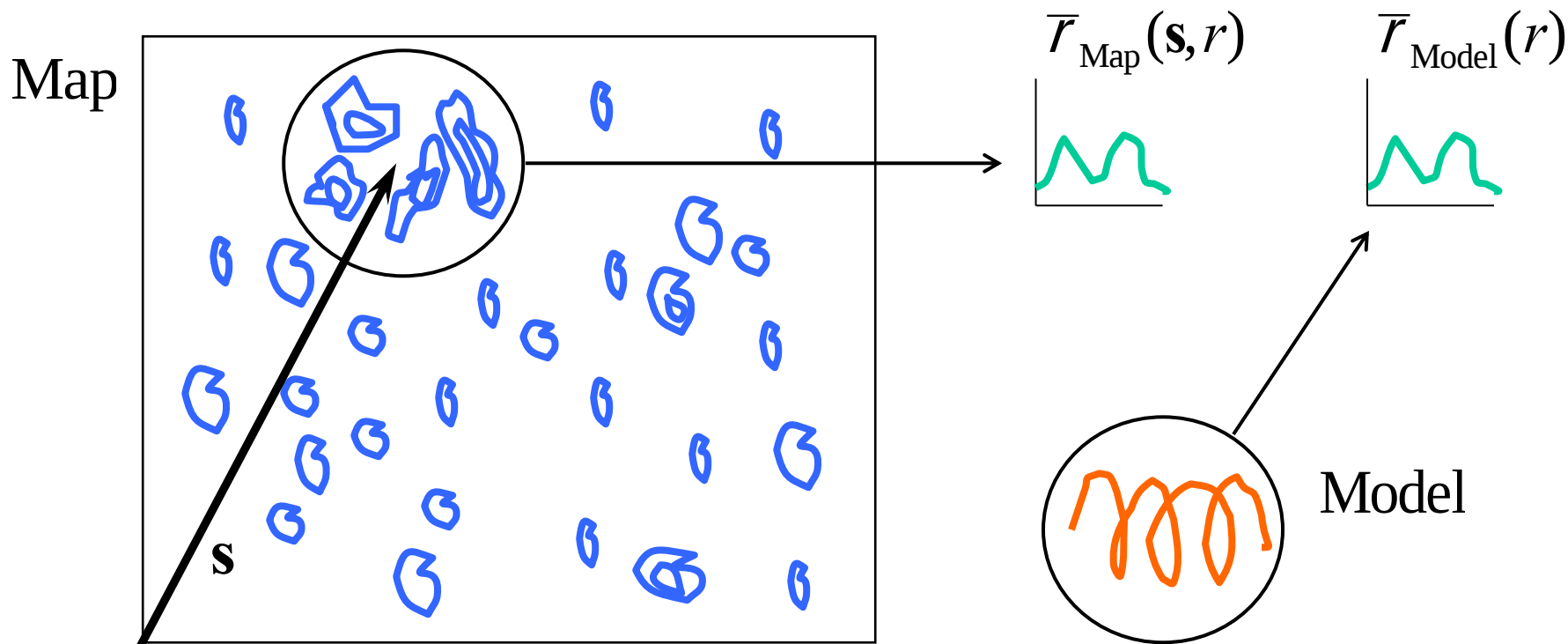
Search in the map

- Calculate 2-1 or 1-1 maps after restrained refinement of partial structure
- Flatten the **map** corresponding to the known substructure
- Calculate structure amplitudes from this map
- Use these **modified amplitudes** in Rotation Function
 - Theoretically quite similar to RF with fixed model in *Phaser*
- And finally – **Phased** TF

SAPTF

Spherically Averaged Phased Translation Function
(FFT based algorithm)

$$\text{SAPTF}(\mathbf{s}) = \int_0^\infty \bar{r}_{\text{Map}}(\mathbf{s}, r) \bar{r}_{\text{Model}}(r) r^2 dr$$



Search in the map with SAPTF

1. Find approximate position:

Spherically Averaged **Phased** Translation Function

2. Find orientation:

Local Phased Rotation Function

– Local search of the orientation in the density

3. Verify and adjust position:

Phased Translation Function

Search in the map with SAPTF

1. Find approximate position:

Spherically Averaged **Phased** Translation Function

2. Find orientation:

Local Rotation Function

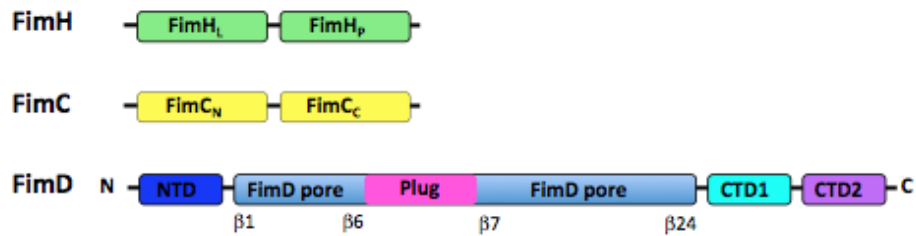
– Structure amplitudes from the density within the SAPTF sphere

3. Verify and adjust position:

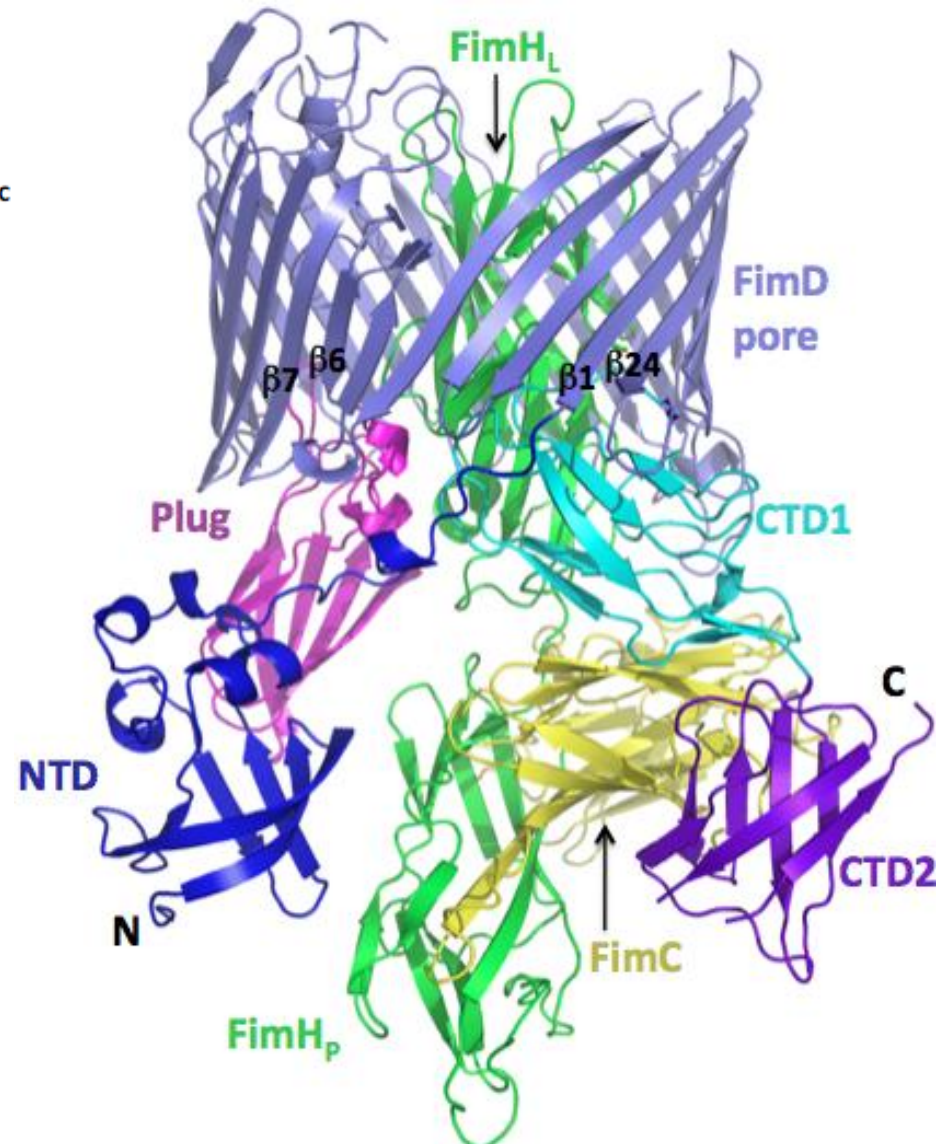
Phased Translation Function

- Local RF is less sensitive than Phased RF to inaccuracy of the model position

Example



- Asymmetric unit two copies
- Resolution 2.8 Å

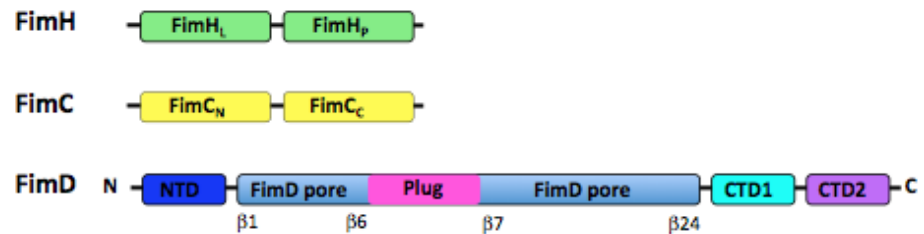


Phane et. al (2011) Nature, 474, 50-53

Usher complex structure solution

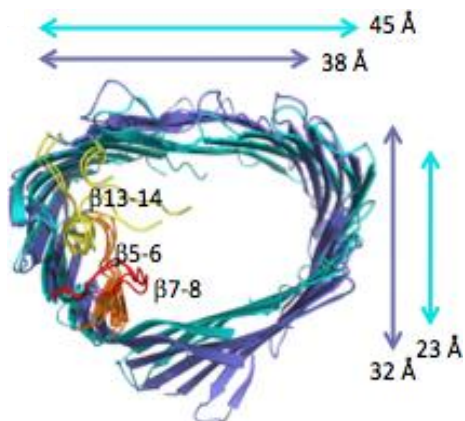
1. Conventional MR

- FimC-N + FimC-C
- FimH-L + FimH-P
- FimD-Pore



2. Jelly body refinement (Refmac)

- FimD-Pore



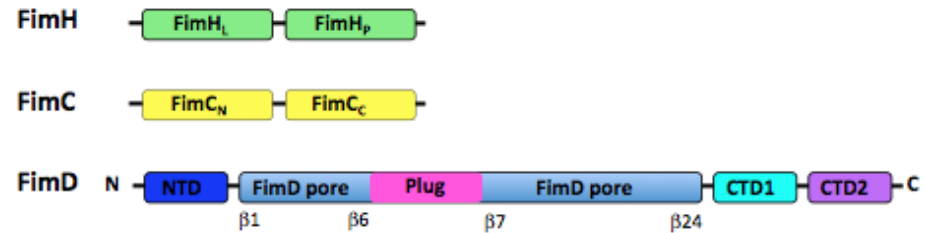
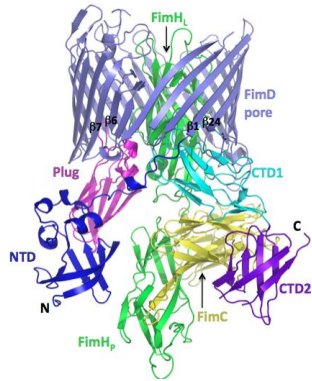
3. Fitting into the electron density

- FimD-Plug
- FimD-NTD
- FimD-CTD-2

4. Manual building

- FimD-CTD-1

Performance of fitting methods



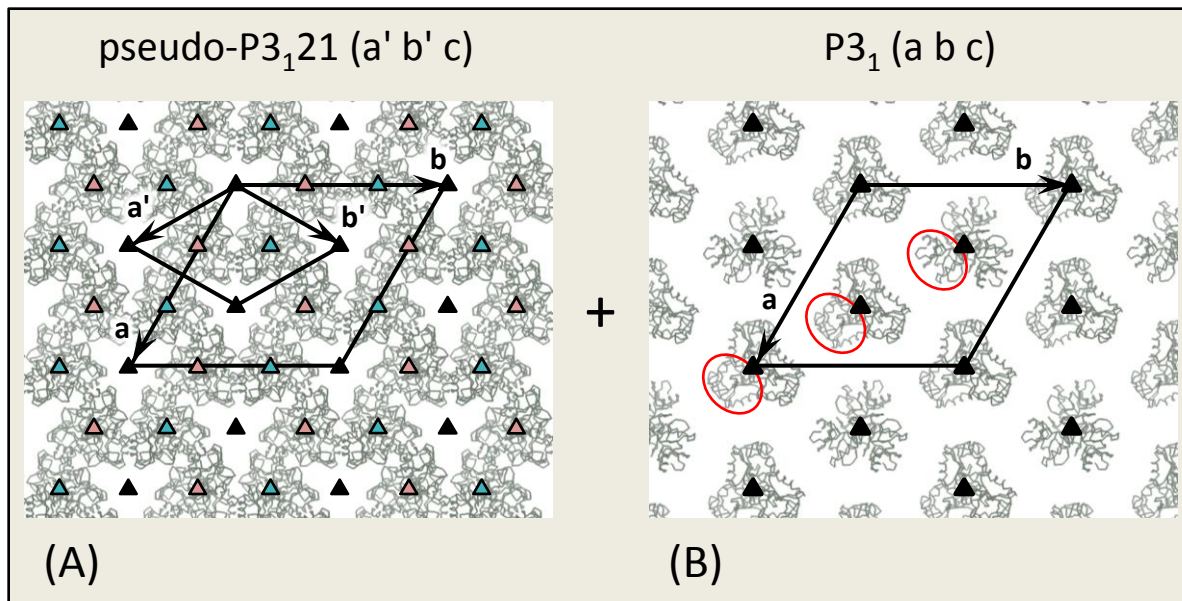
	search model	sequence identity	"Masked" RF PTF <i>prf n</i>	SAPTF PRF PTF <i>prf y</i>	SAPTF Local RF PTF <i>prf s</i>
FimD-Plug	3fip_A	38.5%	2 (2)	– (–)	1 (2)
FimD-NTD	1ze3_D	100%	2 (2)	1 (2)	2 (2)
FimD-CTD-2	3l48_A	33.3%	– (–)	2 (2)	– (–)

Trying several methods is a good practice (also because of cross-validation)

Twinned crystal with pseudo-symmetric substructure

Human macrophage receptor CLEC5A for dengue virus

Watson, A. A. et al. (2011). J Biol Chem 286, 24208-18.

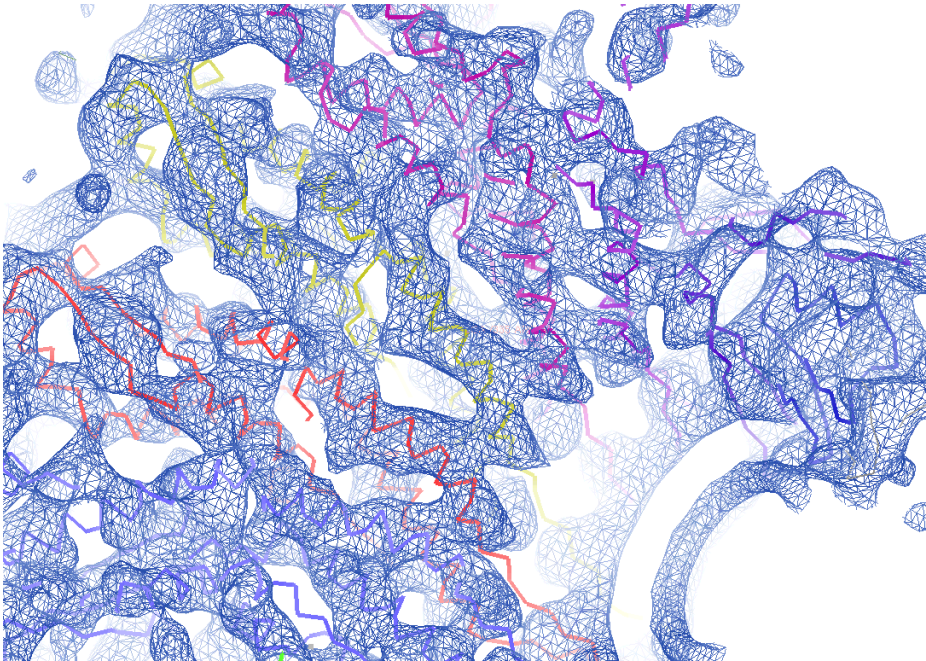


3-fold axes with respect to the true structure:

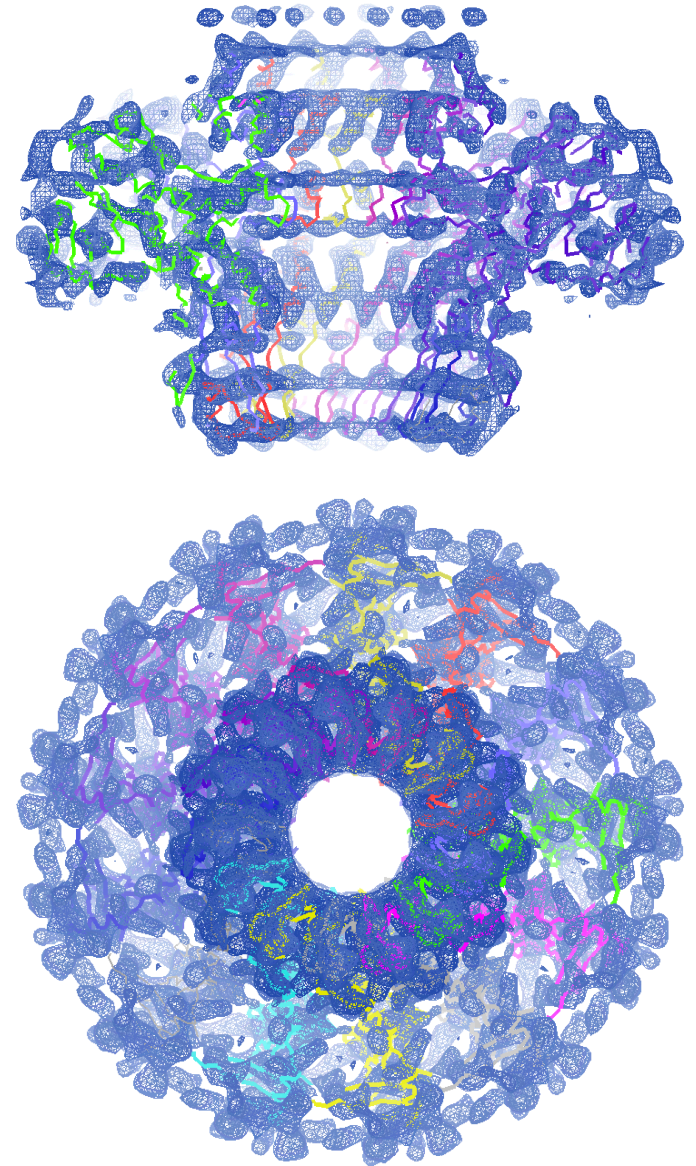
- ▲ crystallographic
- ▲▲ pseudosymmetry for (A)

- Substructure (A): Patterson search (4 copies), search in density (2 copies)
- Substructure (B): Search in the density (3 copies)

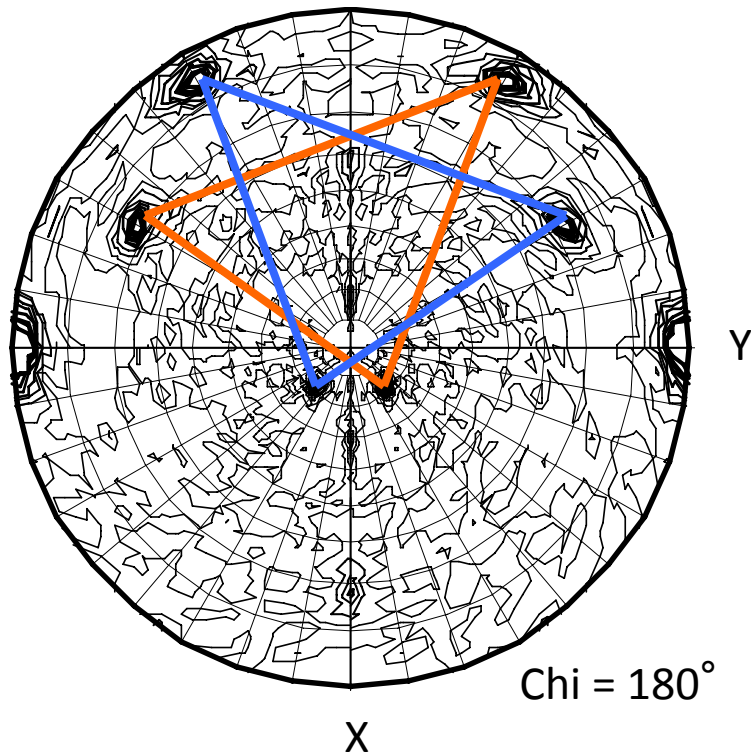
Fitting into EM maps



SPP1 portal protein



Self Rotation Function (SRF)



Preliminary analysis of X-ray data

- Oligomeric state of the protein in crystal
- Selection of oligomeric search model

Limited use

- No clear interpretation or even artifact peaks in high symmetry point groups (e.g. 622)
- different oligomers with the same symmetry

Example of SRF

- Space group P21
- One 222-tetramer in the AU

Locked Rotation Function

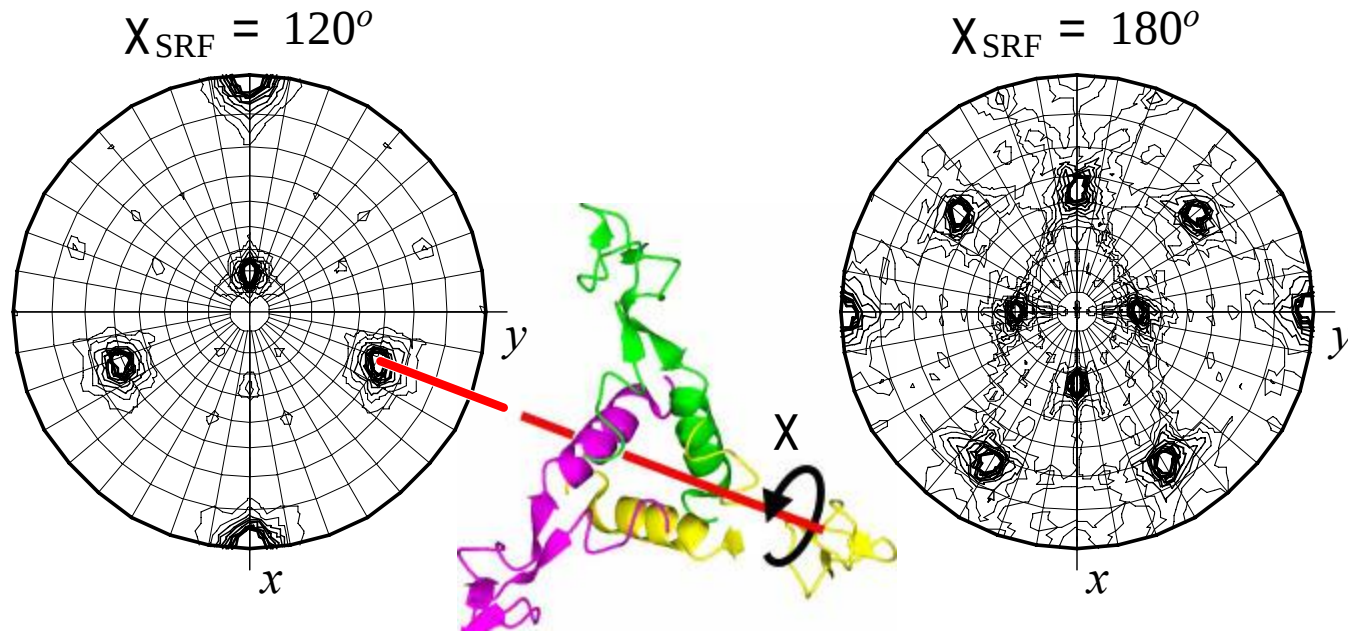
- Uses SRF to derive NCS operations
- Averages RF over NCS operations
- In favorable cases Improves signal to noise ratio in RF

Automatic mode:

```
molrep -f s100.mtz -m monomer.pdb -s s100.seq -i <<+  
lock y  
+
```

There is an option of selecting specific SRF peaks

One-dimensional exhaustive search (exotic case)

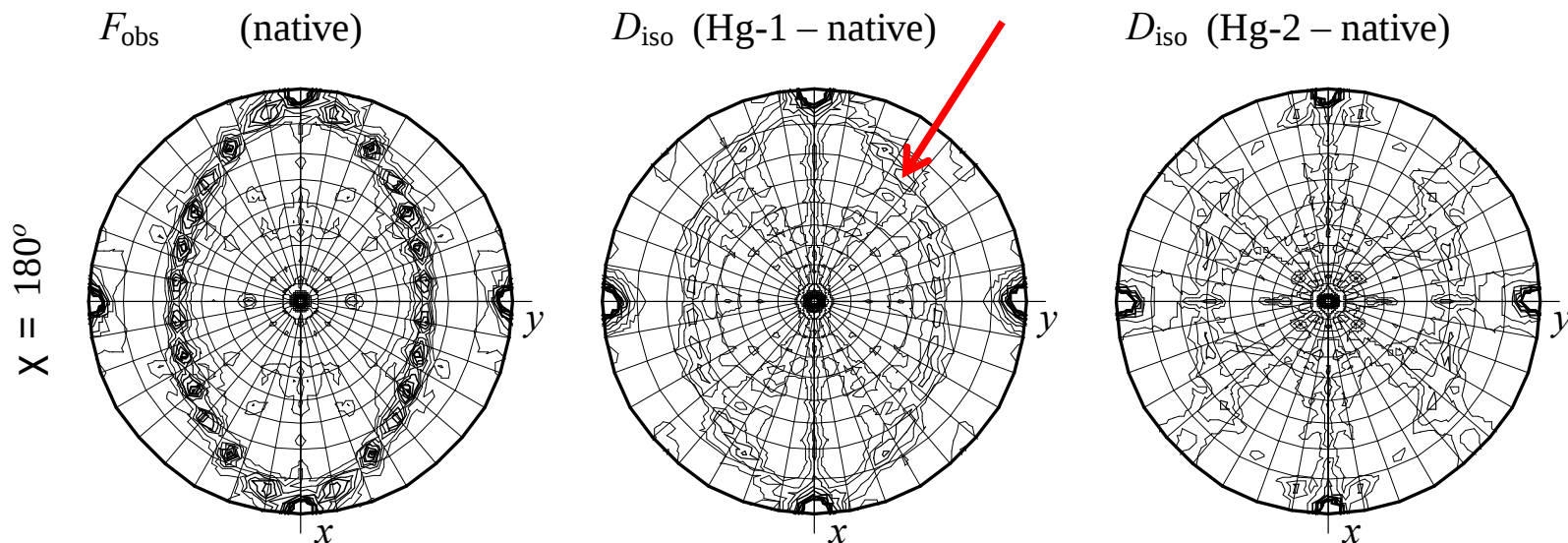


SRF helps restrict dimensionality in an exhaustive search

- Orientation of the ring is known from the analysis of SRF
- Unknown parameter: rotation about 3-fold axis
- One-parametric exhaustive search using TF as score function

MR substructure solution (exotic case)

- Select isomorphous derivative
 - by comparing native SRF and SRF from D-iso



- Hg-substructure is a 13-atom ring (from native SRF analysis)
 - Orientation of the ring is known from the analysis of SRF
 - Unknown parameters: radius of the ring, rotation about 13-fold axis
- Two-parametric exhaustive search

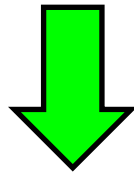
Which direction does MR go?

Automation. Therefore:

- ✗ Collection of tricks
- ✓ Improvement of "standard" methods
- ✓ Better scoring system
- ✓✓ Models

Model improvement

- ✓ Structural information in MR models
- ✓ Extra information in sequence alignment
- ✓ Many homologous structures



- Remove residues that do not align
- Remove "excessive" atoms from aligned residues
- Ensemble models (several superposed models)

Single model correction:

- Chainsaw
- Molrep
- Sculptor

Preparation of ensemble models – fitting models:

- Lsqkab
- ProSMART
- SSM (also in Coot)
- Gesamt

Automated preparation of ensemble models:

- Ensembler

Model modification in MOLREP

```
molrep -f data.mtz -m model.pdb -s target.seq
```

- Performs model correction:
 - Identifies secondary structure in the model
 - Aligns target and model sequences
 - » no deletions or insertions in α -helices or β -strands
 - Retains aligned residues
 - Retains "aligned" atoms in aligned residues
- Adds B-factor to residues exposed to solvent
- Uses sequence identity to down-weight high resolution data

Molecular Replacement in CCP4

MR Programs

- AMoRe
- Molrep
- Phaser

MR Pipelines

- MrBUMP
- Balbes
- AMPLE

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